

# MA4254 Discrete Optimisation

## Midterm Examination Helpsheet

AY2024/25 Semester 1 · Prepared by Tian Xiao @snoidetz

### 1 Introduction

Mixed Integer Linear Programmes: (standard form)

$$\begin{aligned} \min_{x,y} \quad & c^T x + d^T y \\ \text{s.t.} \quad & Ax + By = b \\ & x, y \geq 0, x \in \mathbb{Z}^n, y \in \mathbb{R}^k. \end{aligned}$$

Formulation and Examples:

<p>Item 1, 2, ..., n weight <math>w_1, w_2, \dots, w_n</math> cost <math>c_1, c_2, \dots, c_n</math></p> <p><math>\max_x \sum_{i=1}^n c_i x_i</math> total capacity s.t. <math>\sum_{i=1}^n w_i x_i \leq B</math>, whether we pick <math>i \leftarrow x_i \in \{0, 1\}</math>.</p>	<p>Item 1, 2, ..., n size <math>a_1, a_2, \dots, a_n</math> (<math>a_i</math>) container 1, 2, ..., m size <math>b_1, b_2, \dots, b_m</math> (<math>b_j</math>)</p> <p>binary feasibility problem: whether a feasible point exists. <math>\sum_{i=1}^n x_{ij} = 1 \forall i, \sum_{i=1}^n a_i x_{ij} \leq b_j \forall j</math> <math>x_{ij} \in \{0, 1\} \forall i, j</math> ship capacity <math>y_j \in \{0, 1\}</math></p>
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Knapsack

Shipping containers

<p>Service locations 1, 2, ..., m Customers 1, 2, ..., m <math>C_j</math>: cost for location <math>j</math> to be switched on dij: cost for customer <math>i</math> to be serviced by facility <math>j</math>.</p> <p><math>\min_{x,y} \sum_{j=1}^m C_j y_j + \sum_{i=1}^m \sum_{j=1}^m d_{ij} x_{ij}</math> s.t. <math>\sum_{j=1}^m x_{ij} = 1 \forall i, x_{ij} \leq y_j \forall i, j</math> <math>x_{ij} \in \{0, 1\}, y_j \in \{0, 1\}</math>.</p>	<p>Item 1, 2, ..., n subset <math>F_1, F_2, \dots, F_n</math> (disjoint) Find collection of subsets with highest incidence matrix <math>A_{ij} = \begin{cases} 1, &amp; i \in F_j \\ 0, &amp; \text{otherwise} \end{cases}</math> value.</p> <p><math>x_j \leftarrow \max_x C^T x</math> whether <math>F_j</math> is chosen s.t. <math>A^T x \leq 1, x \in \{0, 1\}^m</math>.</p>
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Facility location (relax)

Packing

<p>Item 1, 2, ..., n subset <math>F_1, F_2, \dots, F_n</math> Optimise objective when all items are covered <math>A_{ij} = \begin{cases} 1, &amp; i \in F_j \\ 0, &amp; \text{otherwise} \end{cases}</math> <math>x_j \leftarrow \min_x C^T x</math> whether <math>F_j</math> is chosen s.t. <math>A^T x \geq 1, x \in \{0, 1\}^m</math></p>	<p>Item 1, 2, ..., n subset <math>F_1, F_2, \dots, F_n</math> Find partition that maximize objective <math>A_{ij} = \begin{cases} 1, &amp; i \in F_j \\ 0, &amp; \text{otherwise} \end{cases}</math> <math>x_j \leftarrow \max_x C^T x</math> whether <math>F_j</math> is chosen s.t. <math>A^T x = 1, x \in \{0, 1\}^m</math></p>
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Covering

Partitioning

One of  $A^T x \geq b$  and  $(A^T x) \geq b'$  needs to be satisfied.

$$\begin{aligned} \max_x \quad & C^T x \\ \text{s.t.} \quad & A^T x \geq y_b \\ & (A^T x) \geq (1-y) b \\ & y \in \{0, 1\}, x \geq 0. \end{aligned}$$

At least  $k$  inequalities from  $\{x: A^T x \geq b\}$  need to be satisfied:

$$\begin{aligned} \max_x \quad & C^T x \\ \text{s.t.} \quad & A^T x \geq b; y_i \\ & \sum y_i \geq k, \\ & y_i \in \{0, 1\}, x \geq 0 \end{aligned}$$

Disjunction

More disjunction

Assume  $A^T x \geq r \forall x \geq 0, x \in C$ , we want  $x \geq 0, x \in C$   
at least  $k$  from  $\{x: A^T x \geq b\}$ .  
Let  $y_i = \begin{cases} 1, & \text{if constraint } i \text{ is satisfied} \\ 0, & \text{otherwise} \end{cases}$   
Then the feasible region is  $A^T x \geq y_i (b_i - r) + r$   
 $\sum y_i \geq k$   
 $y_i \in \{0, 1\}, x \geq 0, x \in C$ .

$m \geq k(x)$ : no. of non-zero entries in  $x$ .  
 $\min_{x \in \{-M, M\}^n} m \geq k(x)$  s.t.  $Ax \leq b$   
 $\Downarrow$  MILP  
 $\min_{x \geq 0} \sum_{i=1}^n z_i$  s.t.  $Ax \leq b$   
 $\forall i, -M z_i \leq x_i \leq M z_i$   
 $x \in \mathbb{R}^n, z \in \{0, 1\}^n$ .

Even more disjunction

Non-linear to linear

People 1, 2, ..., n  
Job 1, 2, ..., n  
Cost of person  $j$  doing job  $i$ :  $C_{ij}$

$\min_{x_{ij}} \sum_{j=1}^n \sum_{i=1}^n C_{ij} x_{ij}$  whether person  $j$  does job  $i$   
s.t.  $\sum_{j=1}^n x_{ij} = 1 \forall i$   
 $\sum_{i=1}^n x_{ij} = 1 \forall j$   
 $x_{ij} \in \{0, 1\} \forall i, j$

$G = (V, E)$   
 $k$ -coloring: Each vertex has a color s.t. adjacent nodes have different color.  
 $\min \sum y_j \rightarrow$  if color  $j$  required  
 $x_{ij} y_j \rightarrow$  if node  $i$  to color  $j$   
s.t.  $\sum x_{ij} = 1$   
 $x_{ij} + x_{kj} \leq y_j \forall (i, k) \in E$   
 $x_{ij}, y_j \in \{0, 1\}$

Job scheduling

$k$ -coloring

Optimal route for driver to traverse  $n$  cities and return.  
Graph  $G = (V, E), S \subseteq \{1, 2, \dots, n\}$   
 $\delta(S)$ : subset of edges from  $S$  to  $S^c$ .

$\min_{x \in \mathbb{Z}^E} \sum_{e \in E} C_e x_e$   
each city once  $\sum_{e \in \delta(S)} x_e = 2 \forall S \subseteq V$   
no  $\Delta$  sub-tour  $\sum_{e \in \delta(S)} x_e \leq 2 \forall S \subseteq V$   
 $x_e \in \{0, 1\}$ .

Optimal route for driver to traverse  $n$  cities and return, but  $C_{ij} \neq C_{ji}$ .  
Graph  $G = (V, E), S \subseteq \{1, 2, \dots, n\}$   
 $\delta^+(S)$ :  $S$  to  $S^c$   $\delta^-(S)$ :  $S^c$  to  $S$ .

$\min_{x \in \mathbb{Z}^E} \sum_{e \in E} C_e x_e$   
s.t.  $\sum_{e \in \delta^+(S)} x_e - \sum_{e \in \delta^-(S)} x_e = 2 \forall S \subseteq V, S \neq \emptyset$   
 $x_e \in \{0, 1\}$ .

TSP

Asymmetric TSP

**Thm. 3.1** Suppose  $P = \{x: Ax = b; x \geq 0\}$  is a non-empty polyhedron, and let  $x \in P$ . The following are equivalent:

- $x$  is a vertex;
- $x$  is an extreme point;
- $x$  is a basic feasible solution with non-negative entries.

### 2 Geometry of Linear Programming

Standard Form: Every LP can be converted to the following standard form (e.g., by adding slack variables):

$$\begin{aligned} \min_x \quad & c^T x \\ \text{s.t.} \quad & Ax = b \\ & x \geq 0. \end{aligned}$$

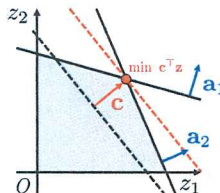
- Maximisation with  $c$  is minimisation with  $-c$ .
- $a_i x_i \leq b \Leftrightarrow a_i x_i + s_i = b; s_i \geq 0$ ;
- $x$  unconstrained  $\Leftrightarrow x^+ - x^-; x^+, x^- \geq 0$ ;

Polyhedron:  $\{x: Ax = b; x \geq 0\}$ .

- Convex sets defined by linear inequalities (equalities).
- Polytype**: Bounded polyhedron.
- Extreme point**: Let  $S \subseteq \mathbb{R}^n$  be a set (polyhedron or otherwise). We say that  $y \in S$  is an extreme point of  $S$  if, whenever  $y = \theta z_1 + (1-\theta)z_2$  for some  $0 < \theta < 1$  and  $z_1, z_2 \in S$ , it must hold that  $y = z_1 = z_2$ .
- Vertex**: Let  $P \subseteq \mathbb{R}^n$  be a polyhedron. We say that  $y \in P$  is a vertex of  $P$  if there is a direction  $c \in \mathbb{R}^n$  such that  $c^T y < c^T z$  for all  $z \in P \setminus \{y\}$ .

Basic Feasible Solutions:

- Assumptions ( $A \in \mathbb{R}^{m \times n}$ ):
  - The polyhedron  $P$  is not empty.
  - The linear map  $A$  has full row rank.
- Basis**:  $m$  linearly dependent columns of  $A$ .
- Basic solution**: Let  $B$  be a basis. Then  $x = B^{-1}b$  for the columns in basis  $> 0$  for the columns not in basis is a basic solution.
- Basic feasible solution**: Basic solution that  $\geq 0$  (feasible).



### 3 Unimodularity and Total Unimodularity

**Polyhedron Integrality**: A polyhedron  $P \subseteq \mathbb{R}^n$  is integral if all its extreme points are integer vectors.

- If so, then solving the relaxation of ILP is tight.

**Unimodularity (U)**: We say that a square matrix  $A \in \mathbb{Z}^{m \times m}$  is unimodular if its determinant is  $\pm 1$ . We say that a matrix  $A \in \mathbb{Z}^{m \times n}$  with full row rank is unimodular if the sub-matrix obtained by taking any  $m$  columns of  $A$  is either singular or unimodular (i.e.,  $\in \{-1, 0, 1\}$ ).

**Thm. 4.1** Let  $A \in \mathbb{Z}^{m \times n}$  be a matrix with full row rank. Then  $A$  is unimodular if and only if the set  $P(b) = \{x: Ax = b; x \geq 0\}$  is integral for any  $b \in \mathbb{Z}^m$  for which the polyhedron  $P(b)$  is non-empty.

*Proof.* This can be proven by using **Cramer's Rule**.

- This applies only to standard form.
- Prop. 4.2** A non-empty bounded polyhedron has at least one extreme point.
- Prop. 4.3** Let  $P$  be a non-empty polyhedron with at least one extreme point. The optimal solution of the LP  $\{\min c^T x: x \in P\}$  is either  $-\infty$  or is attained (possibly non-uniquely) at an extreme point of  $P$ .
- Prop. 4.4** Any non-empty polyhedron of the form  $\{x: Ax = b; x \geq 0\}$  has at least one basic feasible solution (and hence an extreme point).

**Other Results**: (from tutorial)

- $U$  is a square invertible matrix.  $U$  is unimodular if and only if  $U$  and  $U^{-1}$  are both integer-valued matrices (proven by Cramer's rule).
- $U$  is a square invertible matrix.  $U$  is unimodular if and only if for all



$x, Ux$  is integral if and only if  $x$  is integral.

**Unimodular operations:**

- ① Switch two columns;
- ② Multiply a column by  $-1$ ;
- ③ Add an integer multiple of a column to another;

Let  $U$  be a square invertible matrix.  $U$  is unimodular if (and only if) it can be derived from the identity matrix via the above operations.

**Total Unimodularity (TU):** We say that a matrix  $A \in \mathbb{Z}^{m \times n}$  is totally unimodular if the determinant of each square sub-matrix of  $A$  is in  $\{-1, 0, 1\}$ .

**Thm. 4.6** Let  $A \in \mathbb{Z}^{m \times n}$  be a matrix. Then  $A$  is totally unimodular if and only if the set  $P(b) = \{x : Ax \leq b; x \geq 0\}$  is integral for any  $b \in \mathbb{Z}^m$  for which the polyhedron  $P(b)$  is non-empty.

*Proof.*  $A$  is TU

$\Leftrightarrow [A \ I]$  is U (Prop. 4.7)

$\Leftrightarrow \{(x, s) : Ax + s = b; x, s \geq 0\}$  is integral (Thm. 4.1)

$\Leftrightarrow \{x : Ax \leq b; x \geq 0\}$  is integral (Prop. 4.8).

- **Prop. 4.7**  $A$  is TU if and only if  $[A \ I_{m \times m}]$  is unimodular.
- **Prop. 4.8**  $x^*$  is an extreme point of  $P(b) = \{x : Ax \leq b; x \geq 0\}$  if and only if  $[x^* \ s^*] := [x^* \ b - Ax^*]$  is an extreme point of  $Q(b) = \{(x, s) : Ax + s = b; x, s \geq 0\}$ .

**Prop. 4.9**  $A \in \mathbb{Z}^{m \times n}$ . Then  $A$  is TU if and only if  $A^T$  is TU.

**Prop. 4.10**  $A \in \mathbb{Z}^{m \times n}$ . Then  $[A \ I], [A \ A], [A \ -A], [A \ -A \ I], [A \ -A \ I \ -I]$  are all TU.

**Thm. 4.11** Let  $A \in \mathbb{Z}^{m \times n}$  be a matrix. Then  $A$  is TU if and only if the set  $\{x : a \leq Ax \leq b, l \leq x \leq u\}$  is integral for all integral vectors  $a, b, l, u$  for which the polyhedron is non-empty.

**Sufficient Conditions for TU:**

• **Thm. 4.12** A matrix  $A \in \{-1, 0, 1\}^{m \times n}$  is TU if both of the following conditions hold:

- ① Each column of  $A$  contains at most 2 non-zero entries;
- ② It is possible to split the row indices  $\{1, \dots, m\}$  into two disjoint sets  $I_1, I_2$  such that whenever a column (indexed by  $j$ ) has 2 non-zero entries, it holds that

$$\sum_{i \in I_1} A_{ij} = \sum_{i \in I_2} A_{ij}.$$

In other words, if the two non-zeros have the same sign then one lies in  $I_1$  and one lies in  $I_2$ , whereas if the two non-zeros have different signs then both lie in  $I_1$  or both lie in  $I_2$ .

- ▷ **Cor. 4.13** A matrix  $A \in \{-1, 0, 1\}^{m \times n}$  is TU if each of its columns has at most one  $+1$  entry and at most one  $-1$  entry.
- **Thm. 4.14** Let  $A$  be an  $m \times n$  integer-valued matrix, and for any  $\mathcal{J} \subseteq \{1, \dots, n\}$ , let  $A_{\mathcal{J}}$  denote the  $m \times \mathcal{J}$  sub-matrix obtained by keeping only the columns in  $\mathcal{J}$ . Then  $A$  is TU if and only if  $A_{\mathcal{J}}$  admits an equitable column-bicoloring for all non-empty  $\mathcal{J} \subseteq \{1, \dots, n\}$ .

▷ **Equitable bicoloring:** We say that an integer-valued matrix  $A$  admits an equitable column-bicoloring if it is possible to partition the columns indices  $\mathcal{J}$  into two sets  $\mathcal{J}_a$  and  $\mathcal{J}_b$  so that the difference between the sums of the columns in these subsets is a vector with entries in  $\{-1, 0, 1\}$ :

$$\sum_{i \in \mathcal{J}_a} A_i - \sum_{j \in \mathcal{J}_b} A_j \in \{-1, 0, 1\}^m,$$

where  $A_i$  is the  $i$ -th column of  $A$ . Equivalently, there exists some  $z \in \{-1, 1\}^{|\mathcal{J}|}$  such that each entry of  $Az$  has absolute value at most one.

- ▷ **Cor. 4.15**  $A$  is TU if and only if every sub-matrix obtained by taking a non-empty subset of the rows of  $A$  admits an equitable row-bicoloring.
- **Prop. 4.16** The node-edge incidence matrix of an undirected bipartite graph is TU.
  - ▷  $A_{ij} = 1$  if node  $i$  is in edge  $j$  and 0 otherwise.
  - ▷ **Graph matching:** Given a bipartite graph, a matching is a subset of non-intersecting edges (i.e., edges for which no two of them have a common node). A matching is said to be perfect if all nodes are selected.
- **Prop. 4.17** The node-edge incidence matrix of a directed graph is TU.
  - ▷  $A_{ij} = 1$  if edge  $j$  starts from node  $i$ ,  $-1$  if edge  $j$  ends at node  $i$ , 0 otherwise.

**4 Appendix: Mathematical Facts**

**Determinant:**

• Cofactor expansion: For a matrix  $A \in \mathbb{R}^{n \times n}$ , we have

$$\det(A) = \sum_{j=1}^n A_{ij} C_{ij},$$

where  $C_{ij} = (-1)^{i+j} \det(A_{ij})$ .

• **Cramer's Rule**  $A \in \mathbb{R}^{n \times n}$  is invertible. Then the solution to the linear system  $Ax = b$  is given by

$$x_i = \frac{\det(A_i)}{\det(A)},$$

where  $A_i$  is the matrix obtained by replacing the  $i$ -th column of  $A$  with vector  $b$ :

$$[A_1 \ \dots \ A_{i-1} \ b \ A_{i+1} \ \dots \ A_n].$$

•  $\det(A^T) = \det(A)$ .

•  $\det(A^{-1}) = \frac{1}{\det(A)}$ .

•  $\det(AB) = \det(A) \det(B)$ .

**Trace:**

•  $\text{tr}(A + B) = \text{tr}(A) + \text{tr}(B)$ .

•  $\text{tr}(A^T) = \text{tr}(A)$ .

•  $\text{tr}(A^T B) = \text{tr}(AB^T) = \text{tr}(B^T A) = \text{tr}(BA^T)$ .

(P)  $\min c^T x$

s.t.  $A^T_i x \geq b_i \ \forall i \in M^+$ ;

$A^T_i x \leq b_i \ \forall i \in M^-$ ;

$A^T_i x = b_i \ \forall i \in M_0$ ;

$x_j \geq 0 \ \forall j \in N^+$ ;

$x_j \leq 0 \ \forall j \in N^-$ ;

$x_j \in \mathbb{R} \ \forall j \in N^0$ ;

(D)  $\max p^T b$

s.t.  $p_i \geq 0 \ \forall i \in M^+$ ;

$p_i \leq 0 \ \forall i \in M^-$ ;

$p_i$  free  $\forall i \in M_0$ ;

$p^T A_j \leq c_j \ \forall j \in N^+$

$p^T A_j \geq c_j \ \forall j \in N^-$

$p^T A_j = c_j \ \forall j \in N^0$

**Weak duality theorem:** If  $x$  is feasible in (P) and  $p$  is feasible in (D), then  $p^T b \leq c^T x$  and thus

$$\sup_{p \text{ feasible}} p^T b \leq \inf_{x \text{ feasible}} c^T x.$$

- If feasible and  $p^T b = c^T x$ , both  $p$  and  $x$  are optimal.
- Unboundness in one implies infeasibility in another.

**Maximum flow problem:** (P) and (D) can both be infeasible.

$$\max \sum_{(u,v) \in E} f_{uv}$$

s.t.  $0 \leq f_{uv} \leq C_{uv} \ \forall (u,v) \in E$

$\sum_{u:(u,v) \in E} f_{uv} = \sum_{w:(v,w) \in E} f_{vw} \ \forall v \in V \setminus \{s,t\}$

**Minimum cut problem:**

$$\min \sum_{(u,v) \in E} C_{uv} \lambda_{uv}$$

$\{\lambda_{uv}\}_{(u,v) \in E}$

s.t.  $\sum_s \lambda_{sv} = 1, \sum_t \lambda_{vt} = 0, \lambda_{uv} \geq 0 \ \forall (u,v) \in E$

**Shortest path problem:**  $s \rightarrow v_1 \rightarrow v_2 \rightarrow \dots \rightarrow v_k \rightarrow t \in E$ .  $G = (V, E)$  is a directed graph.  $l_e$  is length of  $e$ .

$$\min \sum_{e \in E} l_e x_e$$

s.t.  $\sum_{e \in \delta^-(v)} x_e - \sum_{e \in \delta^+(v)} x_e = 0$

$\sum_{e \in \delta^-(s)} x_e - \sum_{e \in \delta^+(s)} x_e = -1$

$\sum_{e \in \delta^-(t)} x_e - \sum_{e \in \delta^+(t)} x_e = 1$

$x_e \in \{0, 1\}^E$ .

LP relaxation is tight.