

# MA4270 Data Modelling and Computation

## Midterm Examination Helpsheet

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### 1 Perceptron

**Classification Problems:** To learn a classifier  $f_{\theta}$  that classifies labels accurately.

- Dataset:  $\mathcal{D} = \{(\mathbf{x}_t, y_t)\}_{t=1}^n$  where  $\mathbf{x}_t \in \mathbb{R}^d$  and  $y_t \in \{-1, +1\}$ .
- Classifier:  $f_{\theta} : \mathbb{R}^d \rightarrow \{-1, +1\}$ .
  - ▷ Linear classifier:  $f_{\theta} = \text{sign}(\theta^T \mathbf{x})$ .
- Training error:  $\hat{E}(\theta) = \frac{1}{n} \sum_{t=1}^n \text{Loss}(y_t, f_{\theta}(\mathbf{x}_t))$ .
  - ▷  $\text{Loss}(y, \hat{y}) = \mathbb{1}\{\hat{y} \neq y\} = \begin{cases} 1 & \hat{y} \neq y \\ 0 & \text{otherwise} \end{cases}$ .
  - ▷ A dataset is *linearly separable* if  $\exists \theta \left[ \hat{E}(\theta) = 0 \right]$ .

**The Perceptron Algorithm:**

- Initialize  $\theta^{(0)}$  to some value (e.g.,  $\mathbf{0}$ ), and initialize index  $k$  to 0.
- Repeatedly perform the following:
  - ▷ Select the next example  $(\mathbf{x}_t, y_t)$  from the training set and check whether  $\theta^{(k)}$  classifies it correctly.
  - ▷ If it is incorrect (i.e.,  $y_t (\theta^{(k)})^T \mathbf{x}_t < 0$ ), set  $\theta^{(k+1)} \leftarrow \theta^{(k)} + y_t \mathbf{x}_t$  and increment  $k \leftarrow k + 1$ .

- Assumptions:
  - (1) Inputs are bounded:  $\exists R \in (0, \infty) \forall \mathbf{x}_t \in \mathcal{D} \left[ \|\mathbf{x}_t\| \leq R \right]$ .
  - (2) Linearly separable:  $\exists \theta^* \exists \gamma > 0 \left[ \min_{t=1,2,\dots,n} y_t (\theta^*)^T \mathbf{x}_t \geq \gamma \right]$ .
- Convergence: Under the initial vector  $\theta^{(0)} = \mathbf{0}$ , for any dataset  $\mathcal{D}$  satisfying the above assumptions, the perceptron algorithm produces a vector  $\theta^{(k)}$  classifying every example correctly after at most  $k_{\max} = \frac{R^2 \|\theta^*\|^2}{\gamma^2}$  mistakes (and hence update steps).

*Proof.* Let  $R = \max \|\mathbf{x}_t\|$ ,  $\gamma = \min y_t (\theta^*)^T \mathbf{x}_t$  for  $t = 1, 2, \dots, n$ .

- $(\theta^*)^T \theta^{(k)} = (\theta^*)^T (\theta^{(k-1)} + y_t \mathbf{x}_t) \geq (\theta^*)^T \theta^{(k-1)} + \gamma$ . So  $(\theta^*)^T \theta^{(k)} \geq k\gamma$ .
- $\|\theta^{(k)}\|^2 = \|\theta^{(k-1)}\|^2 + 2(\theta^{(k-1)}, y_t \mathbf{x}_t) + \|\mathbf{x}_t\|^2 \leq \|\theta^{(k-1)}\|^2 + \|\mathbf{x}_t\|^2$ . So  $\|\theta^{(k)}\|^2 \leq kR^2$ .
- By Cauchy-Schwarz inequality  $\langle \mathbf{v}, \mathbf{w} \rangle \leq \|\mathbf{v}\| \cdot \|\mathbf{w}\|$ , we have  $1 \geq \frac{(\theta^{(k)}, \theta^*)}{\|\theta^{(k)}\| \cdot \|\theta^*\|} \geq \frac{k\gamma}{\sqrt{kR^2} \|\theta^*\|}$ , hence  $k \leq \frac{R^2 \|\theta^*\|^2}{\gamma^2}$ .

- Margin: Let  $\gamma = \min_{t=1,2,\dots,n} y_t \theta^T \mathbf{x}_t$ . The quantity  $\gamma_{\text{geom}} = \frac{\gamma}{\|\theta\|}$  is the smallest distance from any example  $\mathbf{x}_t$  to the decision boundary specified by  $\theta$ .

### 2 Support Vector Machine (SVM)

**Maximum Margin Classifier:**  $\min_{\theta} \frac{1}{2} \|\theta\|^2$  s.t.  $\forall t \left[ y_t \theta^T \mathbf{x}_t \geq 1 \right]$  (unique).

- SVM with offset:  $\min_{\theta, \theta_0} \frac{1}{2} \|\theta\|^2$  s.t.  $\forall t \left[ y_t (\theta^T \mathbf{x}_t + \theta_0) \geq 1 \right]$ .
  - ▷ Support vectors: On margin  $(y_t (\theta^T \mathbf{x}_t + \theta_0) = 1)$ .
- Soft-margin SVM:  $\min_{\theta, \theta_0, \zeta} \frac{1}{2} \|\theta\|^2 + C \sum_{t=1}^n \zeta_t$  s.t.  $\forall t \left[ y_t (\theta^T \mathbf{x}_t + \theta_0) \geq 1 - \zeta_t \right]$ .
  - ▷  $\zeta = (\zeta_1, \zeta_2, \dots, \zeta_n) \geq \mathbf{0}$  is called *slack variables*.
  - ▷ Support vectors: On margin/within margin/misclassified.
- Hinge-loss formulation:  $\min_{\theta, \theta_0} \frac{1}{2} \|\theta\|^2 + C \sum_{t=1}^n [1 - y_t (\theta^T \mathbf{x}_t + \theta_0)]_+$ .
  - ▷ Hinge loss:  $z \rightarrow [1 - z]_+ = \max\{0, 1 - z\}$ .
  - ▷ Interpretation: Total hinge loss with regularization term  $\frac{1}{2} \|\theta\|^2$ .

### 3 Logistic Regression

**Logistic Likelihood Model:**  $\Pr(y | \mathbf{x}) = \frac{1}{1 + \exp(-y(\theta^T \mathbf{x} + \theta_0))}$ .

- $g(z) = \frac{1}{1 + e^{-z}} \in (0, 1)$  assigns *likelihood* to points.
  - ▷ Scaling the dataset by  $c > 1$  pushes prediction closer to 0 or 1.
  - ▷ Linear classifier chooses the label that is more likely under the logistic model.
  - ▷ Log-odds  $\log \frac{\Pr(y=1|\mathbf{x})}{\Pr(y=-1|\mathbf{x})}$  is a linear function  $\langle \theta, \mathbf{x} \rangle + \theta_0$  of inputs.

- Maximum likelihood estimate (MLE) of parameters:

$$\begin{aligned} (\hat{\theta}, \hat{\theta}_0) &= \arg \max_{\theta, \theta_0} \prod_{t=1}^n \Pr(y_t | \mathbf{x}_t; \theta, \theta_0) \quad (\text{likelihood}) \\ &= \arg \max_{\theta, \theta_0} \prod_{t=1}^n \frac{1}{1 + \exp(-y_t(\theta^T \mathbf{x}_t + \theta_0))} \quad (\text{likelihood}) \\ &= \arg \max_{\theta, \theta_0} \sum_{t=1}^n \log \frac{1}{1 + \exp(-y_t(\theta^T \mathbf{x}_t + \theta_0))} \quad (\text{log-likelihood}) \\ &= \arg \min_{\theta, \theta_0} \sum_{t=1}^n \log \left( 1 + \exp(-y_t(\theta^T \mathbf{x}_t + \theta_0)) \right). \end{aligned}$$

- Regularization:  $\min_{\theta, \theta_0} \frac{1}{2} \|\theta\|^2 + C \sum_{t=1}^n \log \left( 1 + \exp(-y_t(\theta^T \mathbf{x}_t + \theta_0)) \right)$ .
  - ▷ Logistic loss:  $z \rightarrow \log(1 + e^{-z})$ .
  - ▷ Interpretation: Total logistic loss with regularization term  $\frac{1}{2} \|\theta\|^2$ .
- Softmax function:  $\Pr(y = c | \mathbf{x}) = \frac{\exp(\theta_c^T \mathbf{x} + \theta_{0,c})}{\sum_{c'=1}^M \exp(\theta_{c'}^T \mathbf{x} + \theta_{0,c'})}$ .
  - ▷ When  $M = 2$ , we recover logistic model by setting  $(\theta_c, \theta_{0,c}) = (\mathbf{0}, 0)$  for one of the two classes.

### 4 Linear Regression

**Linear Predictor:**  $\hat{y} = \theta^T \mathbf{x} + \theta_0$ .

- Matrix form:  $\hat{\mathbf{y}} = \mathbf{X}\Theta$ , where  $\mathbf{X} = \begin{bmatrix} \mathbf{x}_1^T & 1 \\ \vdots & \vdots \\ \mathbf{x}_n^T & 1 \end{bmatrix}$  and  $\Theta = \begin{bmatrix} \theta \\ \theta_0 \end{bmatrix}$ ,

- Least squares estimate (LSE):  $\hat{\Theta} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$ .
  - ▷ Unique solution if  $\mathbf{X}^T \mathbf{X}$  is invertible.
- Gaussian model:  $y_t = (\theta^*)^T \mathbf{x}_t + \theta_0^* + z_t$ , where  $z_t \sim \mathcal{N}(0, \sigma^2)$ .
  - ▷ Gaussian PDF:  $\mathcal{N}(z; \mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(z-\mu)^2}{2\sigma^2}\right)$ .
  - ▷  $\Pr(y | \mathbf{x}) = \mathcal{N}(y; (\theta^*)^T \mathbf{x} + \theta_0^*, \sigma^2)$ .
  - ▷ Log-likelihood:

$$\log \prod_{t=1}^n \Pr(y_t | \mathbf{x}_t) = \text{const.} - \frac{n}{2} \log \sigma^2 - \frac{1}{2\sigma^2} \sum_{t=1}^n (y_t - \theta^T \mathbf{x}_t - \theta_0)^2.$$

- ▷ MLE of  $\theta$  and  $\theta_0$ :  $(\hat{\theta}, \hat{\theta}_0) = \arg \min_{\theta, \theta_0} \sum_{t=1}^n (y_t - \theta^T \mathbf{x}_t - \theta_0)^2$ .

\*  $\sigma^2$  is assumed to be known.

\* MLE of  $\sigma^2$ :  $\hat{\sigma}^2 = \frac{1}{n} \sum_{t=1}^n (y_t - \hat{\theta}^T \mathbf{x}_t - \hat{\theta}_0)^2$ .

- Gaussian model in matrix form:  $\mathbf{y} = \mathbf{X}\Theta^* + \mathbf{z}$ .

▷ LSE:  $\hat{\Theta} = \Theta^* + (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{z}$ .

\* No bias:  $\mathbb{E}[\hat{\Theta}] = \Theta^*$ .

\* Covariance:  $\text{Cov}[\hat{\Theta}] = \sigma^2 (\mathbf{X}^T \mathbf{X})^{-1}$ .

- Ridge regression:  $(\hat{\theta}, \hat{\theta}_0) = \arg \min_{\theta, \theta_0} \sum_{t=1}^n (y_t - \theta^T \mathbf{x}_t - \theta_0)^2 + \lambda \sum_{j=1}^d \theta_j^2$ .

▷ Closed-form solution (w/o offset):  $\hat{\theta} = (\mathbf{X}^T \mathbf{X} + \lambda \mathbf{I})^{-1} \mathbf{X}^T \mathbf{y}$ .

\*  $\mathbf{X}^T \mathbf{X} + \lambda \mathbf{I}$  is always invertible when  $\lambda > 0$ .

▷ Assuming no offset  $\theta_0$ :

\* Bias:  $\mathbb{E}[\hat{\theta}] - \theta^* = -\lambda (\mathbf{X}^T \mathbf{X} + \lambda \mathbf{I})^{-1} \theta^*$ .

\* Covariance:  $\sigma^2 \left( (\mathbf{X}^T \mathbf{X} + \lambda \mathbf{I})^{-1} - \lambda (\mathbf{X}^T \mathbf{X} + \lambda \mathbf{I})^{-2} \right)$ .

**Bias-Variance Tradeoff:** Decomposition of MSE:

$$\mathbb{E}[\|\hat{\Theta} - \Theta^*\|^2] = \underbrace{\mathbb{E}[\|\hat{\Theta} - \Theta^*\|^2]}_{\text{bias}} + \underbrace{\mathbb{E}[\|\hat{\Theta} - \mathbb{E}[\hat{\Theta}]\|^2]}_{\text{variance}}$$

*Proof.* Let  $\mu = \mathbb{E}[\hat{\Theta}]$ .

① bias =  $\|\mu\|^2 - 2\langle \mu, \Theta^* \rangle + \|\Theta^*\|^2$ .

② variance =  $\mathbb{E}[\|\hat{\Theta}\|^2] - 2\langle \hat{\Theta}, \mu \rangle + \|\mu\|^2 = \mathbb{E}[\|\hat{\Theta}\|^2] - 2\langle \mathbb{E}[\hat{\Theta}], \mu \rangle + \|\mu\|^2 = \mathbb{E}[\|\hat{\Theta}\|^2] - \|\mu\|^2$ .

③ bias + variance =  $\mathbb{E}[\|\hat{\Theta}\|^2] - 2\langle \mu, \Theta^* \rangle + \|\Theta^*\|^2 = \text{LHS}$ .

### Appendix

**Matrix Properties:**

|     |  |   |                                |
|-----|--|---|--------------------------------|
| PSD | $\forall \mathbf{x} \in \mathbb{R}^n \left[ \mathbf{x}^T \mathbf{A} \mathbf{x} \geq 0 \right]$ | $\forall \lambda \left[ \lambda \geq 0 \right]$ | $\Leftrightarrow$ convex       |
| PD  | $\forall \mathbf{x} \neq \mathbf{0} \left[ \mathbf{x}^T \mathbf{A} \mathbf{x} > 0 \right]$     | $\forall \lambda \left[ \lambda > 0 \right]$    | $\Rightarrow$ strictly convex  |
| NSD | $\forall \mathbf{x} \in \mathbb{R}^n \left[ \mathbf{x}^T \mathbf{A} \mathbf{x} \leq 0 \right]$ | $\forall \lambda \left[ \lambda \leq 0 \right]$ | $\Leftrightarrow$ concave      |
| ND  | $\forall \mathbf{x} \neq \mathbf{0} \left[ \mathbf{x}^T \mathbf{A} \mathbf{x} < 0 \right]$     | $\forall \lambda \left[ \lambda < 0 \right]$    | $\Rightarrow$ strictly concave |
| ID  | none of the above  | $\lambda_1 > 0; \lambda_2 < 0$                  | $\Rightarrow$ neither nor      |

- $\mathbf{X}^T \mathbf{X}$  is symmetric and PSD;  $\mathbf{X}^T \mathbf{X} + \lambda \mathbf{I}$  is PD.

• Eig( $\mathbf{A} + \mathbf{I}$ ) = Eig( $\mathbf{A}$ ) + 1. PSD + PD = PD.

• Trace: ① linear ( $\text{Tr}(\mathbb{E}[\mathbf{A}]) = \mathbb{E}[\text{Tr}(\mathbf{A})]$ ); ②  $\mathbf{u}^T \mathbf{v} = \text{Tr}(\mathbf{u}^T \mathbf{v}) = \text{Tr}(\mathbf{v}^T \mathbf{u})$ .

• Derivative:  $\nabla_{\mathbf{x}} \|\mathbf{A} \mathbf{x} + \mathbf{b}\|^2 = 2\mathbf{A}^T (\mathbf{A} \mathbf{x} + \mathbf{b})$ .